

Introduction

- Spatial multiplex imaging allows for the simultaneous visualization and analysis of multiple biomarkers within a single tissue sample while preserving spatial context.
- Biopsies are taken from each patient, and Regions of Interest (ROIs) are identified from Tumor Micro Arrays (TMA), which are slides containing one or more patient tumors.
- For each ROI, the locations and types of each cell in the ROI are obtained.

Data Description

We have the **spatial multiplex images** for the lung cells of **153 patients** specifying the positions and cell types in an image with the patient's demographic information (Gender, Age, Stage, Adjuvant Therapy, MHCII Status).

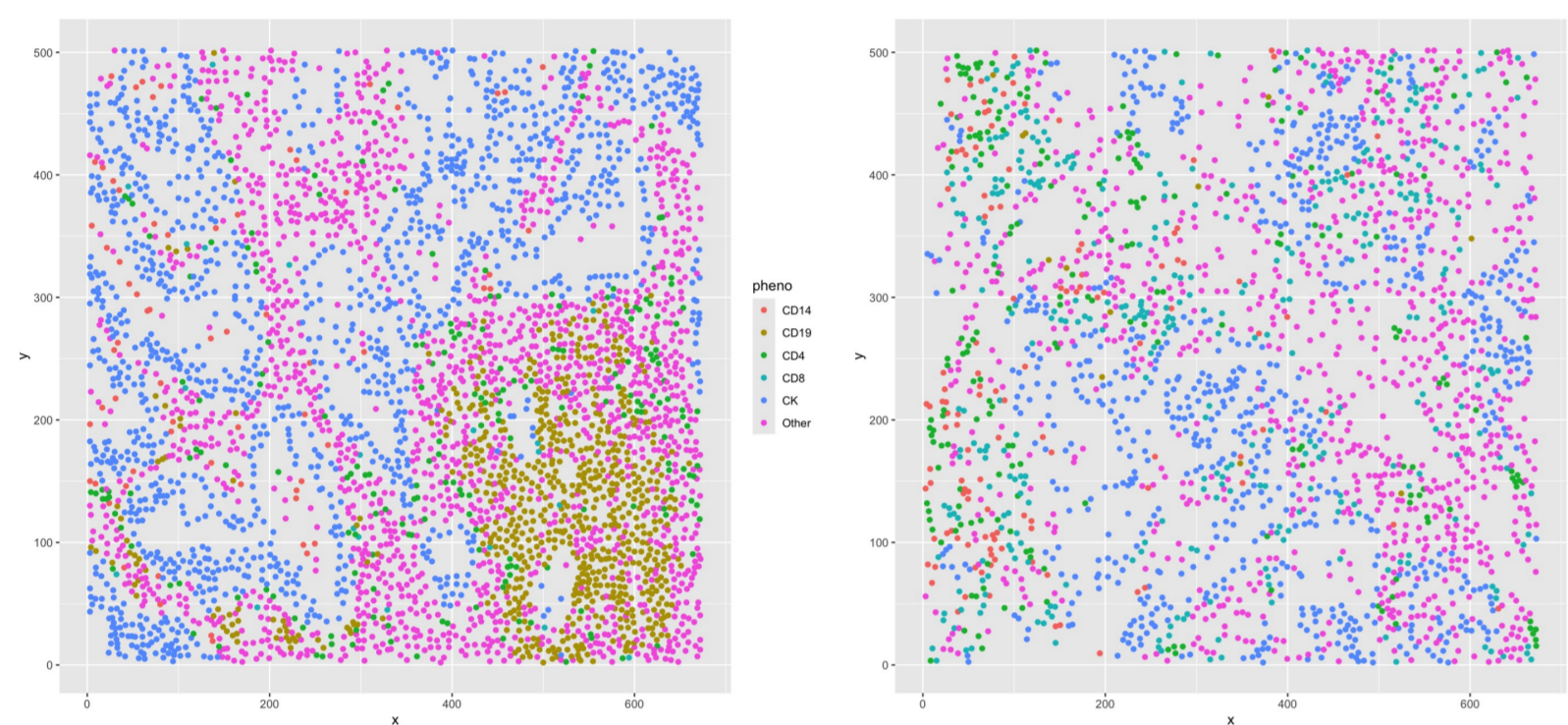


Figure 1. Visualization of the cell structure

Estimating Intensities

- We estimate spatial point pattern intensities for each cell type per patient using a kernel density estimator and we convert matrices to vectors.
- Combine vectors row-wise and perform PCA, retaining components explaining 90% of the variation.
- Resulting in a matrix of principal components for all cell types.

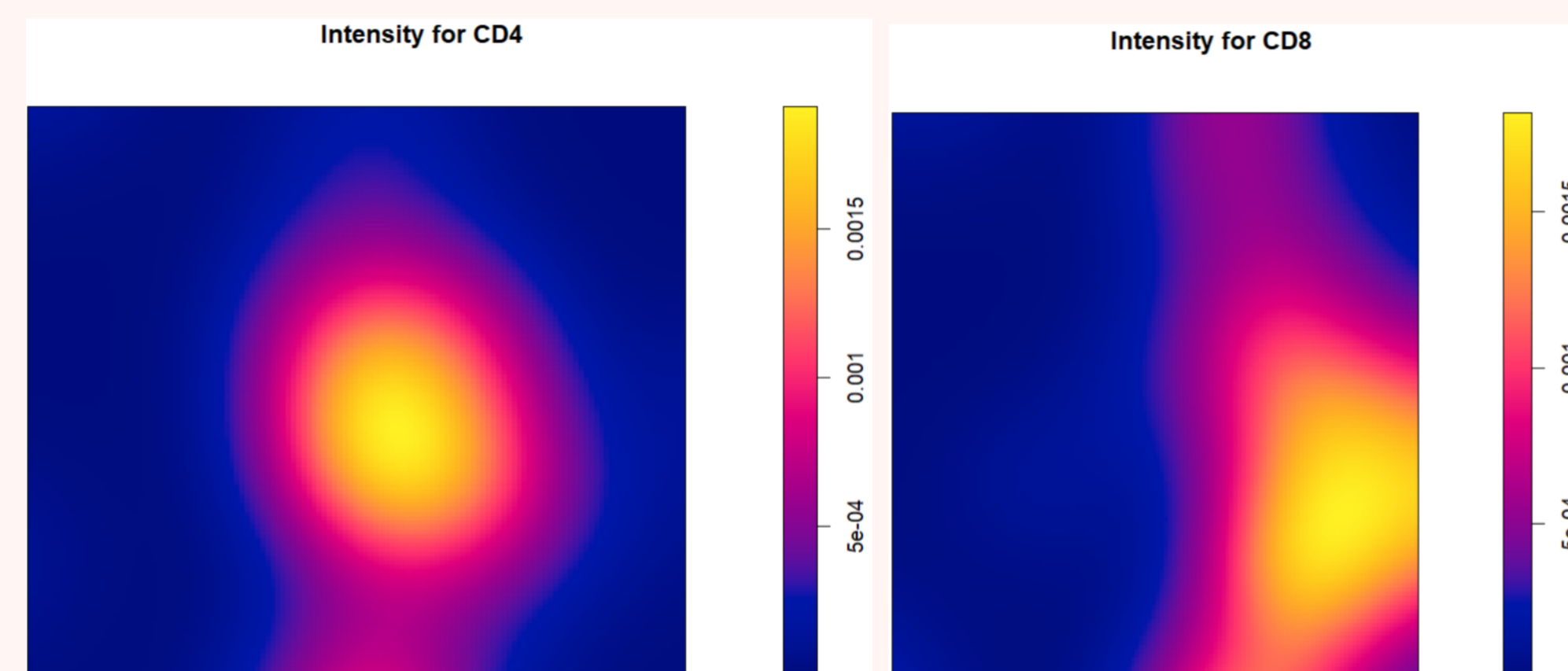


Figure 2. Visualizing the intensities

K functions and K cross functions

- For a spatial point pattern, K -function at a particular radius r is defined as

$$\hat{K}(r) = \frac{|A|}{n(n-1)} \sum_{i=1}^n \sum_{j \neq i}^n \mathbf{1}(d(c_i, c_j) \leq r) e_{ij}$$

where $|A|$ is the area of the image and $\{c_i\}_{i=1}^n$ are the position of the points.

- Another version of these functions are K -cross and permuted K -functions ($\tilde{K}(r)$) which are used to extract spatial information embedded in a multiplex image.
- For each image we find **deciles** of $|\hat{K}(r) - \tilde{K}(r)|$ and use as spatial covariates.

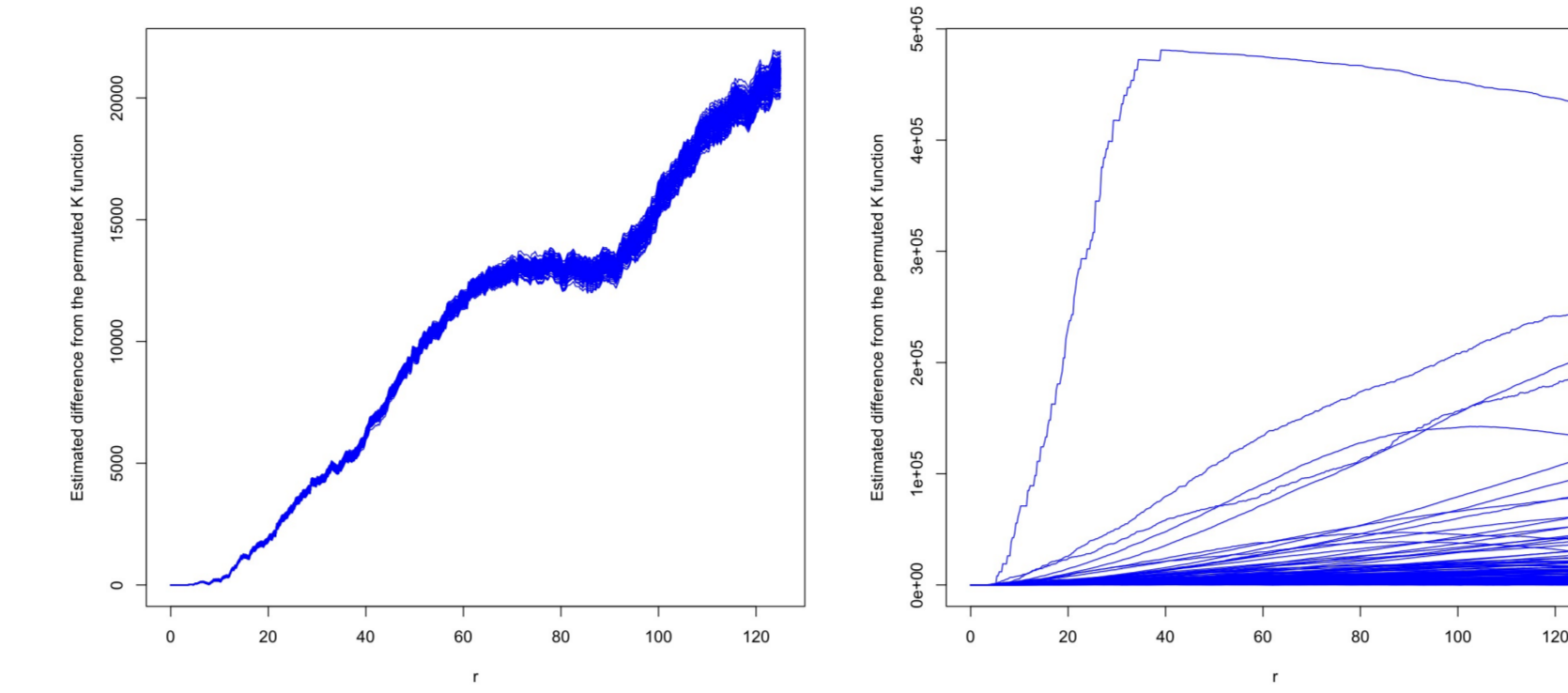
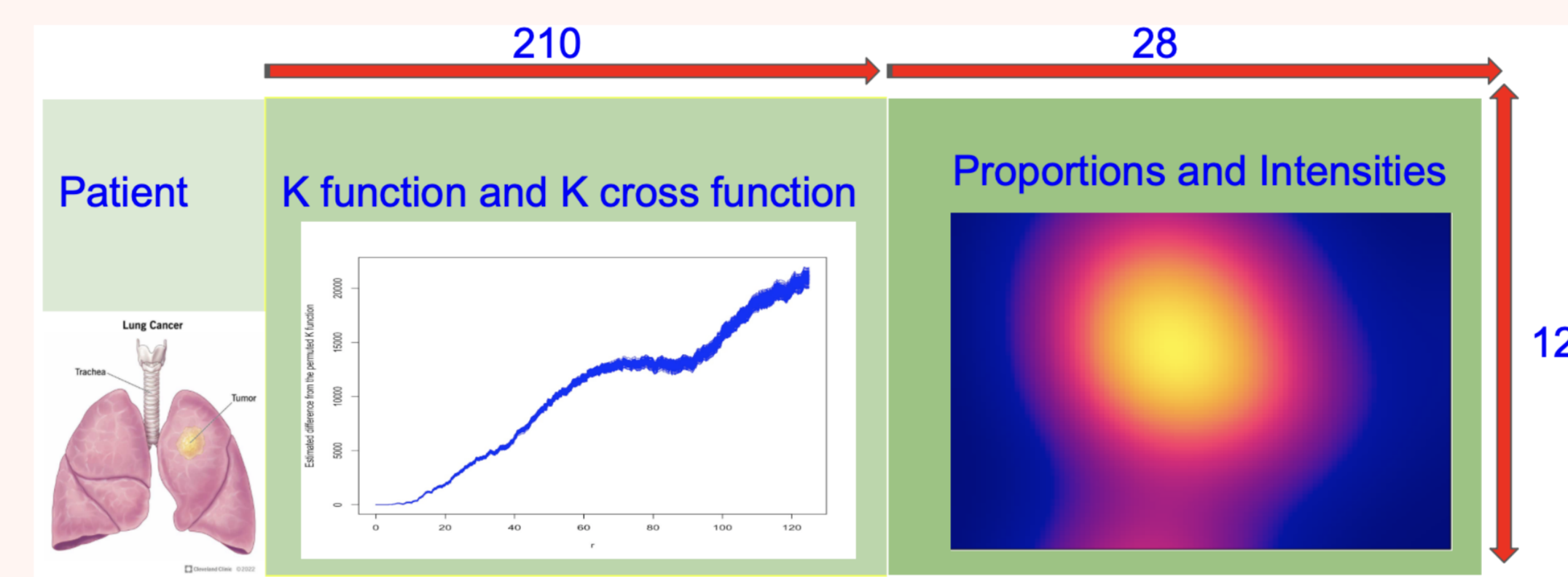


Figure 3. Visualization of $|K(r) - \tilde{K}(r)|$

The Final Dataset

- The principal components of the estimated intensities, deciles of the K -Functions, and the proportions of the cell types in each image are combined as the final dataset having **127 patients** and **238 spatial features**. Clustering is done based on this dataset after scaling columnwise.

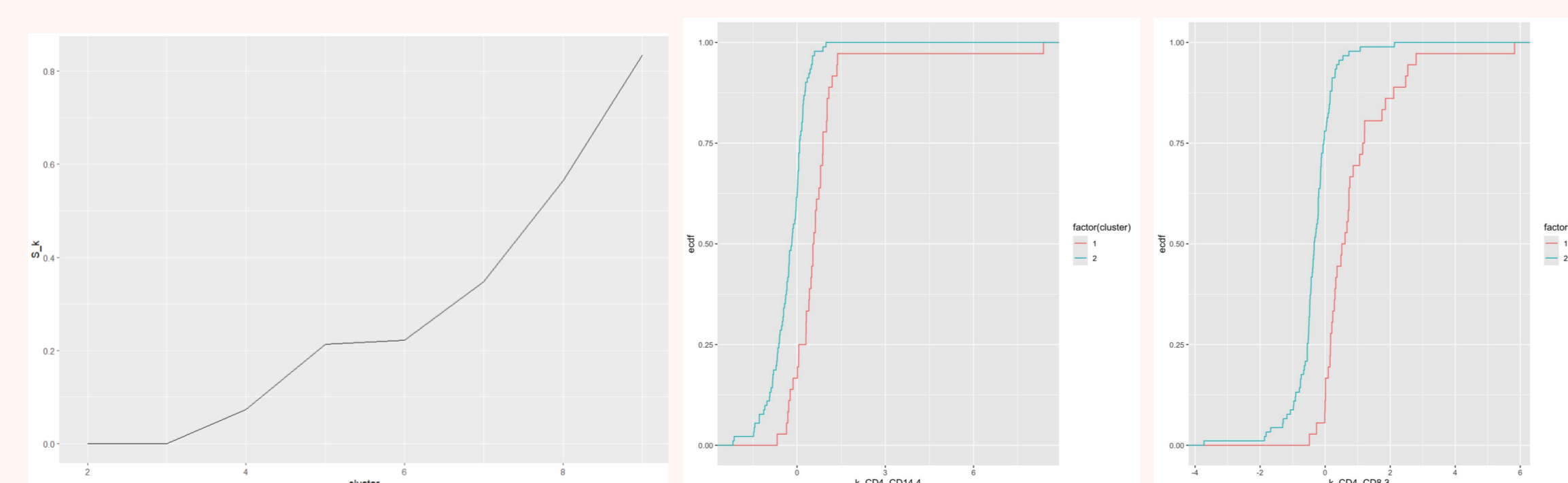


Clustering

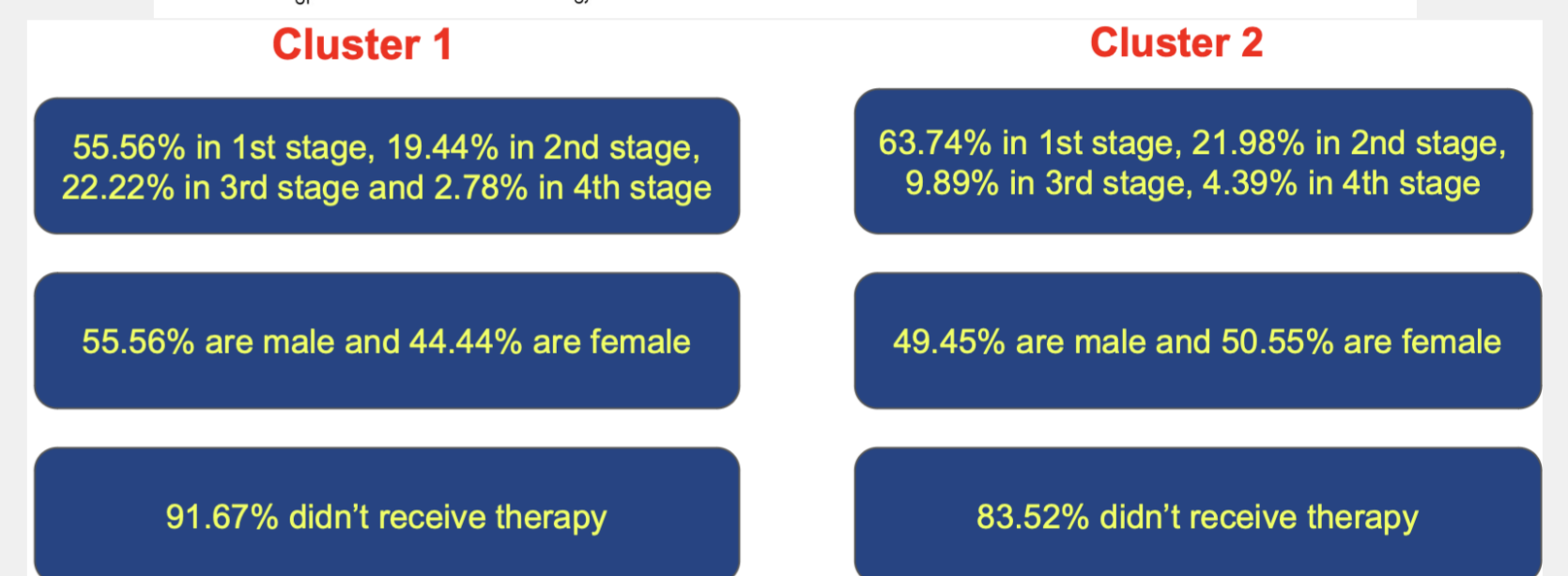
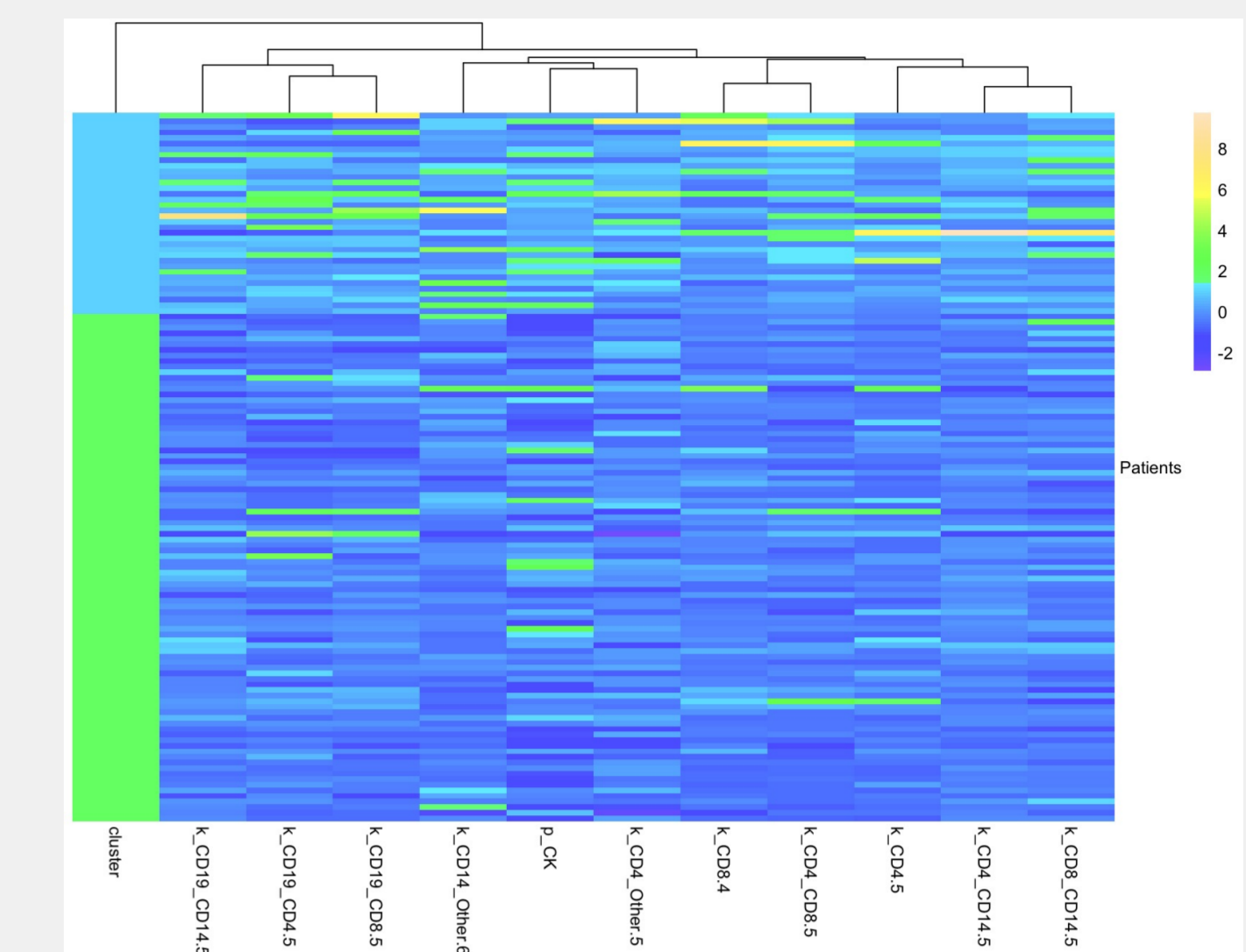
- In the combined dataset we use **Partitioning around Medoid (PAM)** algorithm for robust clustering of patients according to all the spatial features collected from the images.
- For a particular no of clusters (k) the PAM algorithm searches for k representative objects in a data set (k medoids) and then assigns each object to the closest medoid to create clusters aiming towards minimizing the intercluster variation.

Choosing the optimal no of Clusters (K)

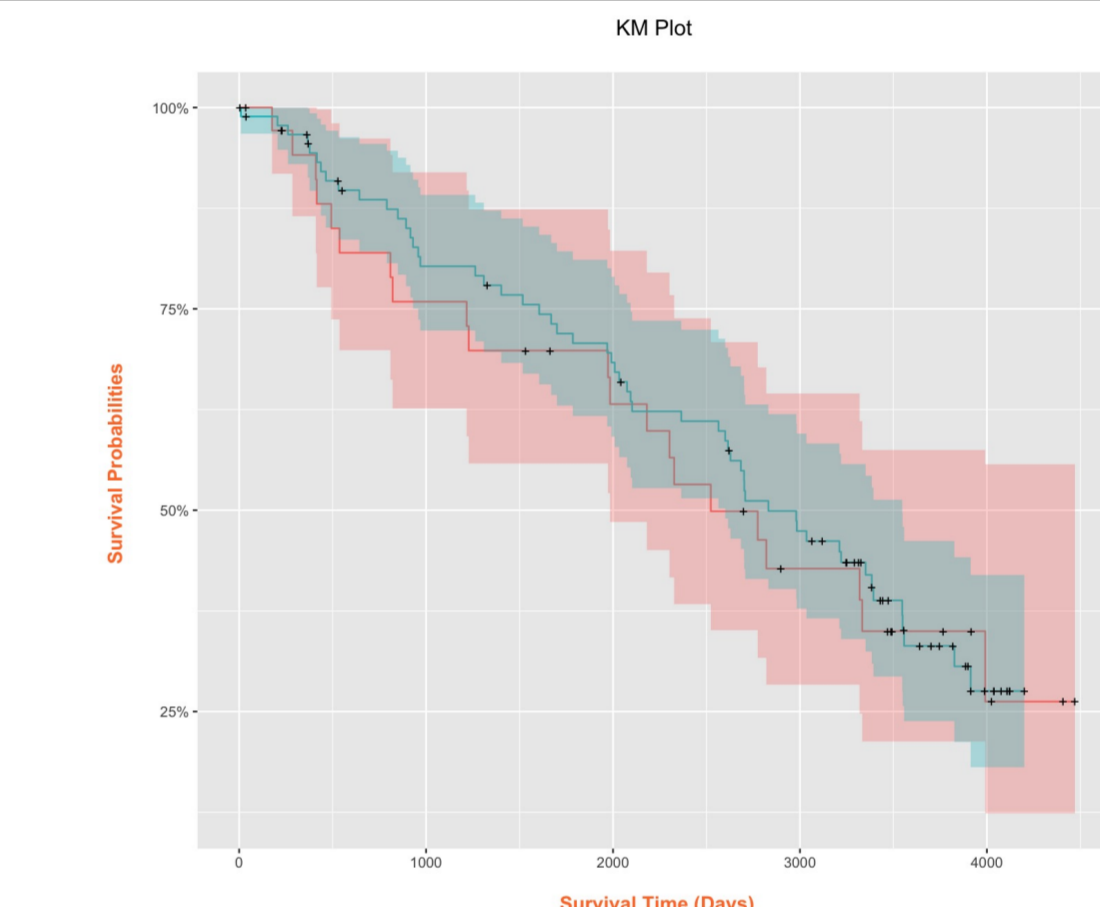
- For a k , let A_1, \dots, A_k be the data matrices broken cluster-wise where a column represents a feature.
- For the r th feature, let p_r be the median of $p_{i,j}^r$ over $(i, j) : i, j \in \{1, 2, \dots, n\}, i \leq j$ where for each of $\binom{n+1}{2}$ pairs (i, j) , $p_{i,j}^r$ is the p-value for the exact two-sample Kolmogorov-Smirnov test between the vectors $A_i[r]$ and $A_j[r]$.
- Let $p_{(1)} \leq p_{(2)} \leq \dots \leq p_{(238)}$ be the ordered values p_1, \dots, p_{238} . (There are 238 features in total). Let $S_k = p_{(1)} + \dots + p_{(24)}$ and choose the K which minimizes S_k .
- The optimal number of clusters turns out to be 2.



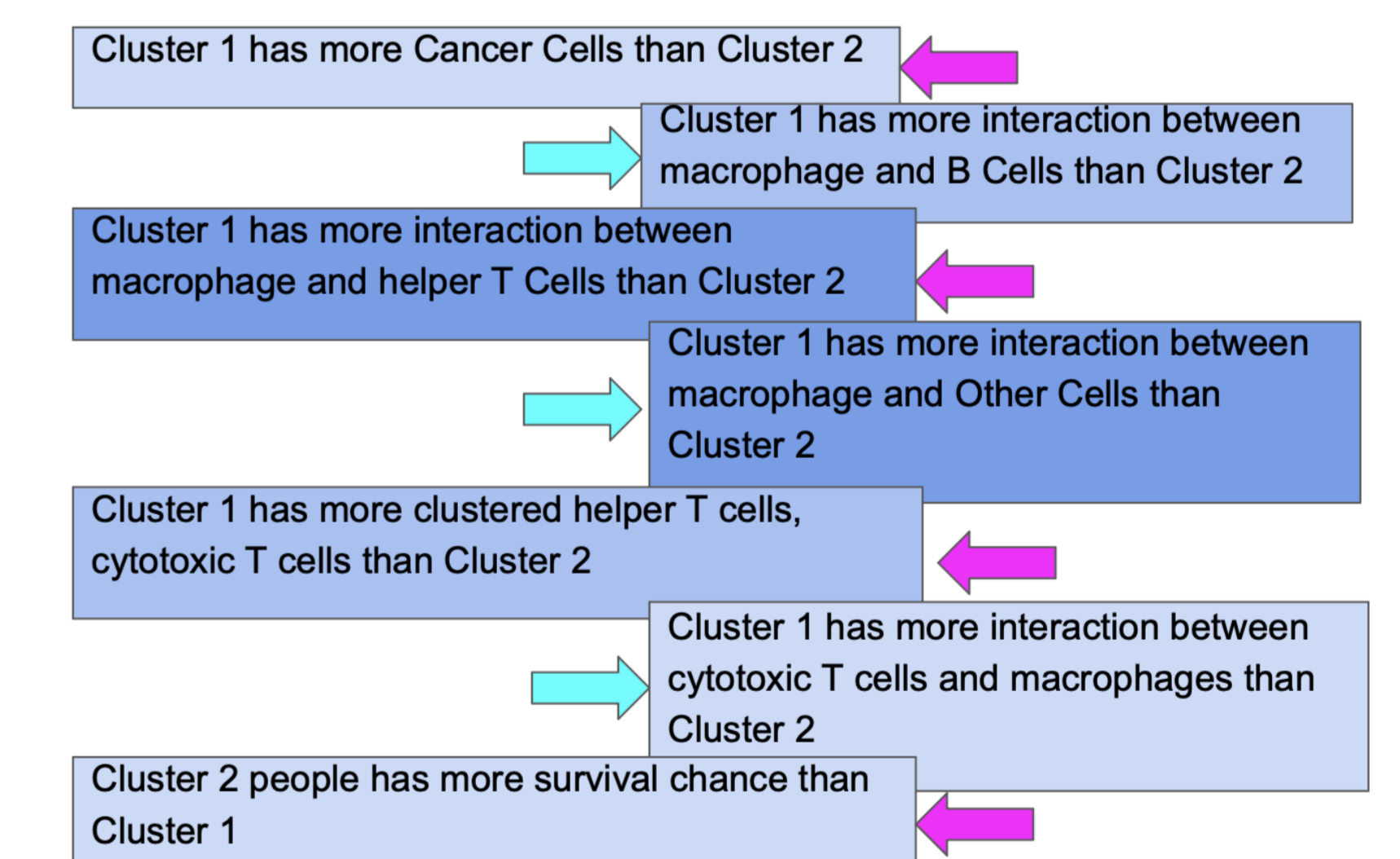
Feature Variation across Clusters



Clusterwise Survival Analysis



Conclusions



Limitations

- In this study we can not capture the joint spatial effect of three or more cell types.
- The Principal Components of the intensities are not very much interpretable.
- Choosing deciles in place of other quantiles can be justified more statistically by some sensitivity analysis.

Appendix - Abbreviations for Cell Types

CD14 (macrophages), CD4 (helper T cells), CD8 (cytotoxic T cells), CD19 (B cells), CK (Cancer Cells), and Other Cell Types